# LECTURE 23: ORTHOGONALITY-AWESOMENESS

Tuesday, November 19, 2019 5:47 PM

**Today:** What makes orthogonality so awesome? There will be **MANY** miracles!

## I- ORTHOGONAL SETS

**Definition:**  $\mathcal{B}$  is orthogonal if for any two <u>different</u> vectors u and v in  $\mathcal{B}$ , we have  $u \cdot v = 0$ 

Example: Is 
$$\mathscr{B} = \left\{ \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \end{bmatrix} \right\}$$
 orthogonal?  
u v

u • v = 2 (-3) + 3 (2) = 0, *s*o YES

(Note: No need to check v • u because v • u = u • v = 0
No need to check u • u because need <u>different</u> vectors)

#### Example:

(a) Is 
$$\mathscr{B} = \left\{ \begin{bmatrix} 1\\0\\1 \end{bmatrix}, \begin{bmatrix} -1\\4\\1 \end{bmatrix}, \begin{bmatrix} 2\\1\\-2 \end{bmatrix} \right\}$$
 orthogonal?

(Seems like there's a million different things to check, but really only need to check 3 things)

$$\mathbf{u} \cdot \mathbf{v} = \begin{bmatrix} 1\\0\\1 \end{bmatrix} \cdot \begin{bmatrix} -1\\4\\1 \end{bmatrix} = -1 + 0 + 1 = 0$$

$$u \cdot w = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = 2 + 0 - 2 = 0$$
  

$$v \cdot w = \begin{bmatrix} -1 \\ 4 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = -2 + 4 - 2 = 0$$
  
(b) Is  $\mathscr{B}$  linearly independent?  
Neat Fact: Any orthogonal set without the 0 vector is linearly  
independent!  
So YES  
Why? Suppose a u + b v + c w = 0 (show a = b = c = 0)  
Dot with u: (au + bv + cw) \cdot u = 0 \cdot U = 0  
a u \cdot u + b v u + c w u = 0  
(by orthogonality)  
a (u \cdot u) = 0  
+0  
= > a = 0 (since u = 0)  
Similarly, dot with v to get b = 0 and dot with w to get c = 0

**Note:** In particular, here  $\mathcal{B}$  is a LI set in R<sup>3</sup> with 3 vectors, hence it's

a Basis for R<sup>3</sup> !

Moral: Orthogonality is NICE, it simplifies a lot of things that we had trouble with before

Find a, b, c such that x = au + bv + cw

(Usually a pain to do because it required row-reduction, but here none of that stuff!)

Trick: Dot with u:  $x \cdot u = (au + bv + cw) \cdot u = a u \cdot u + b y u + c w u = a u \cdot u$ a u•u = x•u a = <u>x•u</u> u•u Here:  $\begin{bmatrix} 0 \\ 4 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \underline{6} = 3$   $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ a =

Similarly: Dot with v  

$$b = \frac{x \cdot v}{v \cdot v}$$

$$b = \int_{4}^{2} \int_{1}^{2} \int_{1}^{-1} \int_{1}^{-1} = \frac{2}{18} = \frac{1}{9}$$

$$c = \frac{x \cdot w}{w \cdot w}$$

$$c = \frac{\begin{pmatrix} 2 \\ 0 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}}{\begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}} = \frac{-4}{9}$$

$$\int_{-2}^{2} \int_{1}^{2} \int_{-2}^{1} \int_{-2}^{2} = \frac{-4}{9}$$
Says:  

$$\begin{cases} 2 \\ 0 \\ 4 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \frac{1}{9} \begin{pmatrix} -1 \\ 4 \\ 1 \end{pmatrix} + \frac{-4}{9} \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}$$

$$x = a \quad u + b \quad v + c \quad w$$

(Again, imagine doing this with row-reduction, here we get a direct formula!)

**Summary:** If  $\mathcal{B} = \{u, v, w\}$  is orthogonal and x = au + bv + cw, then

 $a = \frac{x \cdot u}{u \cdot u} \qquad b = \frac{x \cdot v}{v \cdot v} \qquad c = \frac{x \cdot w}{w \cdot w}$ 

Make sure to know this formula, we'll use it over and over again!

**Hugging analogy:** Suppose x is walking down the street and just wants to hug everyone. First, x hugs u (=  $x \cdot u$ ) and then u is so happy it hugs itself (=  $u \cdot u$ ), then x hugs v (=  $x \cdot v$ ) and v hugs itself (=  $v \cdot v$ ), and finally x hugs w (=  $x \cdot w$ ) and w hugs itself (=  $w \cdot w$ )

### II- ORTHONORMAL SETS

Let's power up and define orthonormal sets (= super orthogonal sets), which are even nicer than orthogonal sets

#### Example:

(a) Is 
$$\mathcal{B} = \left\langle \begin{bmatrix} 3 \\ 4 \end{bmatrix}, \begin{bmatrix} -4 \\ 3 \end{bmatrix} \right\rangle$$
 orthogonal?  
u v

 $u \cdot v = 3(-4) + 4(3) = 0$ , so yes

(b) Is  ${\mathcal B}$  orthonormal?

**Definition:** Orthonormal = Orthogonal + Each vector has length 1

$$\begin{bmatrix} 1\\1 \end{bmatrix}^{=} \begin{pmatrix} \frac{7}{5} \\ \frac{3}{5} \end{bmatrix} \begin{pmatrix} \frac{3}{5} \\ \frac{4}{5} \end{bmatrix}^{+} \begin{pmatrix} \frac{-1}{5} \\ \frac{5}{3} \end{pmatrix} \begin{bmatrix} -\frac{4}{5} \\ \frac{3}{5} \end{bmatrix}$$
 (WOW)

Summary: If  $\mathcal{B} = \{u, v, w\}$  is orthonormal and x = au + bv + cw, then

a = x · u b = x · v c = x · w (Even simpler!)

# III- ORTHOGONAL COMPLEMENTS

(Completely unrelated, but *complements* our discussion of orthogonality)

**Example:** Find all the vectors  $\mathbf{x}$  in  $\mathbb{R}^3$  that are orthogonal to

u =	ן 1	and	v =	[ 1 ]
	0			1

Picture: X

Suppose 
$$\mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$
 is orthogonal to u and v, then:  

$$\begin{cases} \mathbf{x} \cdot \mathbf{u} = 0 \\ \mathbf{x} \cdot \mathbf{v} = 0 \end{cases}$$

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} x + z = 0 \\ x + y = 0 \end{cases} = \left( \begin{array}{c} 1 & 0 & 1 \\ 1 & 1 & 0 \end{array} \right) \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
Row-reduce: 
$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \stackrel{o}{\rightarrow} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \end{bmatrix} \stackrel{o}{\rightarrow} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} x + z = 0 \\ y = z \end{bmatrix} = \left( \begin{array}{c} x \\ z \end{bmatrix} = z \\ y = z \end{bmatrix}$$



# (Could use cross-products, but this technique works in ANY dimension!)

