

HW 8 - SOLUTIONS

#19

(a) INTEGRATING $U_{xy} = c$ WITH RESPECT TO x , WE GET

$$U_y = \tilde{G}(y) \quad \text{WHERE } \tilde{G} \text{ IS ARBITRARY}$$

AND INTEGRATING THIS WITH RESPECT TO y , WE GET

$$U(x, y) = F(x) + \int \tilde{G}(y) dy, \quad \text{WHERE } F \text{ IS ARBITRARY}$$

NOW IF G IS ARBITRARY, THEN WE CAN ALWAYS WRITE

$$G \text{ AS } \int \tilde{G}(y) dy, \quad \text{NAMELY WITH } \tilde{G} = Gy,$$

$$\text{AND THEREFORE } U(x, y) = F(x) + G(y),$$

WHERE F AND G ARE ARBITRARY

$$(b) \quad U_x = U_z \frac{dz}{dx} + U_m \frac{dm}{dx} = U_z + U_m$$

$$U_t = U_z \frac{dz}{dt} + U_m \frac{dm}{dt} = U_z - U_m$$

$$\begin{aligned} \text{HENCE } U_{xx} &= (U_x)_z + (U_x)_m = (U_z + U_m)_z + (U_z + U_m)_m \\ &= U_{zz} + U_{mz} + U_{zm} + U_{mm} \\ &= U_{zz} + 2U_{zm} + U_{mm} \end{aligned}$$

$$\begin{aligned} \text{AND } U_{tt} &= (U_t)_z - (U_t)_m = U_{zz} - U_{mz} - U_{zm} + U_{mm} \\ &= U_{zz} - 2U_{zm} + U_{mm} \end{aligned}$$

$$\begin{aligned}
 \text{so } U_{tt} - U_{xx} &= \cancel{U_{zz}} + 2U_{zm} + \cancel{U_{mm}} \\
 &= \cancel{U_{zz}} + 2U_{zm} - \cancel{U_{mm}} \\
 &= 4U_{zm}
 \end{aligned}$$

AND THEREFORE $U_{tt} - U_{xx} = 0 \Leftrightarrow 4U_{zm} = 0 \Leftrightarrow U_{zm} = 0$

(c) FROM (b), WE GET $U_{tt} - U_{xx} = 0 \Rightarrow U_{zm} = 0$

AND FROM (a) WITH z REPLACING x AND m REPLACING y , WE GET

$$U(z, m) = F(z) + G(m)$$

THAT IS, $U(x, t) = F(x+t) + G(x-t)$

Now $U(x, 0) = F(x) + G(x) = g(x)$

$$U_t(x, t) = F'(x+t) - G'(x-t)$$

$$\begin{aligned}
 \text{so } U_t(x, 0) &= F'(x) - G'(x) = h(x) \Rightarrow F(x) - G(x) = \int_0^x h(s) ds \\
 &\Rightarrow F(x) - G(x) = \int_0^x h(s) ds + C
 \end{aligned}$$

Now solving for F & G in $\begin{cases} F(x) + G(x) = g(x) \\ F(x) - G(x) = \int_0^x h(s) ds + C \end{cases}$

WE GET $F(x) = \frac{1}{2} \left(g(x) + \int_0^x h(s) ds + C \right)$ (ADDING BOTH EQ)

$$G(x) = \frac{1}{2} \left(g(x) - \int_0^x h(s) ds - C \right)$$
 (SUBTRACTING BOTH EQ)

Ans so :

$$\begin{aligned}
 U(x,t) &= F(x+t) + G(x-t) \\
 &= \frac{1}{2} g(x+t) + \frac{1}{2} \int_0^{x+t} h(s) ds + \frac{c}{2} + \frac{1}{2} g(x-t) - \frac{1}{2} \int_0^{x-t} h(s) ds - \frac{c}{2} \\
 &= \frac{1}{2} (g(x+t) + g(x-t)) + \frac{1}{2} \left(\int_0^{x+t} h(s) ds - \int_0^{x-t} h(s) ds \right) \\
 U(x,t) &= \frac{1}{2} (g(x+t) + g(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} h(s) ds
 \end{aligned}$$

WHICH IS D'ALEMBERT'S FORMULA

#21: (a) WE KNOW :

$$\left\{ \begin{array}{l} E_t^1 = B_{x_2}^3 - B_{x_3}^2 \\ E_t^2 = B_{x_3}^1 - B_{x_1}^3 \\ E_t^3 = B_{x_1}^2 - B_{x_2}^1 \end{array} \right. \quad \left\{ \begin{array}{l} B_t^1 = E_{x_3}^2 - E_{x_2}^3 \\ B_t^2 = E_{x_1}^3 - E_{x_3}^1 \\ B_t^3 = E_{x_2}^1 - E_{x_1}^2 \end{array} \right.$$

1) THEN $E_{tt}^1 = (B_t^3)_{x_2} - (B_t^2)_{x_3} = E_{x_2 x_2}^1 - E_{x_1 x_2}^2 - E_{x_1 x_3}^3 + E_{x_3 x_3}^1$

BUT $\text{DIV}(E) = 0 \Rightarrow E_{x_1}^1 + E_{x_2}^2 + E_{x_3}^3 = 0$
 $\Rightarrow E_{x_1 x_1}^1 + E_{x_2 x_1}^2 + E_{x_3 x_1}^3 = 0$
 $\Rightarrow E_{x_1 x_2}^2 + E_{x_1 x_3}^3 = -E_{x_1 x_1}^1$

HENCE $E_{tt}^1 = E_{x_1 x_1}^1 + E_{x_2 x_2}^2 + E_{x_3 x_3}^3 = \Delta E^1$

SIMILARLY FOR E_2 AND E_3 , HENCE $E_{tt} - \Delta E = 0$

2) AND $B_{tt}^1 = (E_t^2)_{x_3} - (E_t^3)_{x_2} = B_{x_3 x_3}^1 - B_{x_1 x_3}^3 - B_{x_1 x_2}^2 + B_{x_2 x_2}^1$

BUT $\text{DIV}(B) = 0 \Rightarrow B_{x_1}^1 + B_{x_2}^2 + B_{x_3}^3 = 0$
 $\Rightarrow B_{x_1 x_1}^1 + B_{x_1 x_2}^2 + B_{x_1 x_3}^3 = 0$

$$\Rightarrow B_{x_1 x_2}^2 + B_{x_1 x_3}^3 = -B_{x_1 x_1}^1$$

$$\text{HENCE } B_{tt}^1 = B_{x_1 x_1}^1 + B_{x_2 x_2}^2 + B_{x_3 x_3}^3 = \Delta B^1$$

SIMILARLY FOR B^2 & B^3 , HENCE $B_{tt} - \Delta B = 0$

(8) NOTE SEE END OF THE COURSE FOR AN ALTERNATE DERIVATION:

$$\text{WE KNOW: } \begin{cases} U_{tt}^1 - \mu \Delta U^1 - (\lambda + \mu) (U_{x_1 x_1}^1 + U_{x_2 x_1}^2 + U_{x_3 x_1}^3) = 0 \\ U_{tt}^2 - \mu \Delta U^2 - (\lambda + \mu) (U_{x_1 x_2}^1 + U_{x_2 x_2}^2 + U_{x_3 x_2}^3) = 0 \\ U_{tt}^3 - \mu \Delta U^3 - (\lambda + \mu) (U_{x_1 x_3}^1 + U_{x_2 x_3}^2 + U_{x_3 x_3}^3) = 0 \end{cases}$$

$$(1) \text{ THEN } W_{tt} = (U_{x_1}^1)_{tt} + (U_{x_2}^2)_{tt} + (U_{x_3}^3)_{tt}$$

$$= \mu \Delta U_{x_1}^1 + (\lambda + \mu) (U_{x_1 x_1 x_1}^1 + U_{x_2 x_1 x_1}^2 + U_{x_3 x_1 x_1}^3)$$

$$+ \mu \Delta U_{x_2}^2 + (\lambda + \mu) (U_{x_1 x_2 x_2}^1 + U_{x_2 x_2 x_2}^2 + U_{x_3 x_2 x_2}^3)$$

$$+ \mu \Delta U_{x_3}^3 + (\lambda + \mu) (U_{x_1 x_3 x_3}^1 + U_{x_2 x_3 x_3}^2 + U_{x_3 x_3 x_3}^3)$$

$$= \mu \Delta U_{x_1}^1 + (\lambda + \mu) ((U_{x_1}^1)_{x_1 x_1} + (U_{x_1}^1)_{x_2 x_2} + (U_{x_1}^1)_{x_3 x_3})$$

$$+ \mu \Delta U_{x_2}^2 + (\lambda + \mu) ((U_{x_2}^2)_{x_1 x_1} + (U_{x_2}^2)_{x_2 x_2} + (U_{x_2}^2)_{x_3 x_3})$$

$$+ \mu \Delta U_{x_3}^3 + (\lambda + \mu) ((U_{x_3}^3)_{x_1 x_1} + (U_{x_3}^3)_{x_2 x_2} + (U_{x_3}^3)_{x_3 x_3})$$

$$= \mu \Delta U_{x_1}^1 + (\lambda + \mu) \Delta U_{x_1}^1 + \mu \Delta U_{x_2}^2 + (\lambda + \mu) \Delta U_{x_2}^2 + \mu \Delta U_{x_3}^3 - (\lambda + \mu) \Delta U_{x_3}^3$$

$$= (\lambda + 2\mu) \Delta (U_{x_1}^1 + U_{x_2}^2 + U_{x_3}^3) = (\lambda + 2\mu) \Delta W$$

THEREFORE $W_{tt} - (1+2r)\Delta W = 0$

$$\begin{aligned}
 (2) \quad W_{tt}^1 &= U_{x_2 t t}^3 - U_{x_3 t t}^2 \\
 &= (U_{tt}^3)_{x_2} - (U_{tt}^2)_{x_3} \\
 &= (\mu \Delta U_{x_2}^3 + (1+r)(U_{x_1 x_3 x_2}^1 + U_{x_2 x_3 x_2}^2 + U_{x_3 x_3 x_2}^3)) \\
 &\quad - (\mu \Delta U_{x_3}^2 + (1+r)(U_{x_1 x_2 x_3}^1 + U_{x_2 x_2 x_3}^2 + U_{x_3 x_2 x_3}^3))
 \end{aligned}$$

$$\Rightarrow W_{tt}^1 = \mu \Delta (U_{x_2}^3 - U_{x_3}^2) = \mu \Delta W^1$$

HENCE $W_{tt}^1 - \mu \Delta W^1 = 0$, AND SIMILARLY FOR W^2 & W^3

HENCE $W_{tt} - \mu \Delta W = 0$

(#22) DIFFERENTIATING THE FIRM'S PDE WITH RESPECT TO t , WE GET

$$U_{tt} = -U_{xt} + d(V_t - U_t)$$

DIFFERENTIATING THE FIRM'S PDE WITH RESPECT TO x , WE GET

$$U_{xx} = -U_{xt} + d(V_x - U_x)$$

SUBTRACTING BOTH EQUATIONS, WE GET

$$\begin{aligned}
 U_{tt} - U_{xx} &= \cancel{-U_{xt}} + d(V_t - U_t) + \cancel{U_{xt}} + d(U_x - V_x) \\
 &= d(V_t - U_t + U_x - V_x) \quad (*)
 \end{aligned}$$

BUT NOW ADDING BOTH PDE, WE GET

$$U_t + V_t + U_x - V_x = 0 \Rightarrow U_x - V_x = -U_t - V_t$$

HENCE (*) BECOMES:

$$U_{tt} - U_{xx} = d(V_t - U_t - U_t - V_t) = -2dU_t$$

$$\Rightarrow U_{tt} + 2dU_t - U_{xx} = 0$$

IN A SYMMETRIC MANNER, WE OBTAIN $V_{tt} + 2dV_t - V_{xx} = 0$

NOTE

ALTERNATE SOLUTION TO $\nabla^2 z(B)$ (THANKS, JAMIE!)

(1) WE KNOW
$$U_{tt} - \mu \Delta U - (\lambda + 2\mu) \text{DIV}(\text{DIV}(U)) = 0$$

TAKING THE DIV
$$\text{DIV}(U_{tt}) - \mu \text{DIV}(\Delta U) - (\lambda + 2\mu) \text{DIV}(\text{DIV}(\text{DIV}(U))) = 0$$

$$(\text{DIV}(U))_{tt} - \mu \Delta(\text{DIV}(U)) - (\lambda + 2\mu) \Delta(\text{DIV}(U)) = 0$$

NOTE

$$\begin{aligned} \text{DIV}(\Delta U) &= (\Delta U^2)_{x_1} + (\Delta U^2)_{x_2} + (\Delta U^2)_{x_3} \\ &= \Delta(U_{x_1}^2 + U_{x_2}^2 + U_{x_3}^2) = \Delta(\text{DIV}(U)) \end{aligned}$$

$$W_{tt} - \mu \Delta W - (\lambda + 2\mu) \Delta W = 0$$

$$\boxed{W_{tt} - (\lambda + 2\mu) \Delta W = 0}$$

(2) THIS TIME TAKING CURL, WE GET

$$\text{curl}(U_{tt}) - \mu \text{curl}(\Delta U) - (\lambda + 2\mu) \text{curl}(\text{DIV}(\text{DIV}(U))) = 0$$

$$(\text{curl}(U))_{tt} - \mu \Delta(\text{curl}(U)) = 0 \rightarrow \text{curl}(\Delta U) = (\Delta U_{x_1}^2 - \Delta U_{x_2}^2, \dots)$$

$$\boxed{W_{tt} - \mu \Delta W = 0}$$

$$\begin{aligned} &= \Delta(U_{x_1}^2 - U_{x_2}^2, \dots) \\ &= \Delta \text{curl}(U) \end{aligned}$$