

05/19/20

Sec 11.5. The Rayleigh - Ritz Method

$$\begin{aligned} & - (p(x)y'(x))' + q(x)y(x) = f(x) \\ \text{for } & 0 \leq x \leq 1, \quad y(0) = y(1) = 0. \\ & p(x) > 0, \quad q(x) \geq 0 \end{aligned}$$

- Variational Problems (weak formulation)

$$\begin{aligned} \text{Find } & y \in C_0^1[0, 1] \text{ such that} \\ & \int_0^1 p(x)y'(x)u'(x) + q(x)y(x)u(x) dx \\ & = \int_0^1 f(x)u(x) dx \end{aligned}$$

for all $u \in C_0^1[0, 1]$.
(from integration by parts)



$$\begin{aligned} & y \in C_0^1[0, 1] \text{ minimizes} \\ & I[u] = \int_0^1 p[u']^2 + q[u]^2 - 2fu \, dx. \end{aligned}$$

\Rightarrow It is hard to find such $y \in C_0^1[0, 1]$
because the space $C_0^1[0, 1]$ is infinite
dimensional.

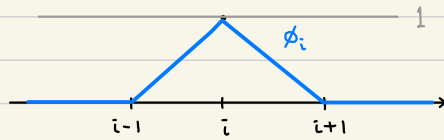
- Rayleigh - Ritz method

Find $y_h \in V_h[0, 1]$ such that $\int_0^1 p y_h' u_h' + q y_h u_h dx = \int_0^1 f u_h dx$

for all $u_h \in V_h[0, 1]$.
(from the variational problem)

• Piecewise linear basis

$$u_h = \sum_i c_i \phi_i$$

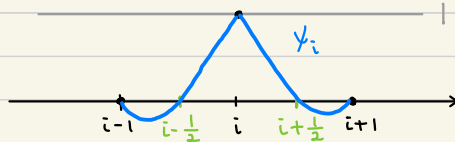


$\dim(V_h) = \#$ of mesh points

boundary condition.
-2

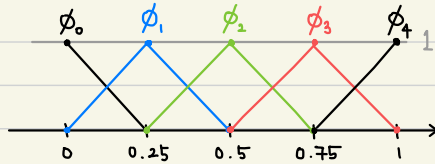
• Piecewise quadratic basis

$$u_h = \sum_i d_i \psi_i$$



$\dim(V_h) = 2 \times (\# \text{ of mesh points}) - 1$

ex) $-y'' = 1, \quad 0 \leq x \leq 1,$
 $y(0) = y(1) = 0, \quad h = 0.25$



$$y_h(x) = \sum_{i=0}^4 c_i \phi_i(x)$$

(c_0, c_1, \dots, c_4)

Find $y_h \in V_h$ such that $\int_0^1 y_h' \phi_j' dx = \int_0^1 \phi_j dx$ test function \Rightarrow basis function.

for all $0 \leq j \leq 4$.

(because ϕ_j are basis functions with $\dim(V_h) = 5$)

$$y(0) = y(1) = 0 \quad \Rightarrow \quad c_0 = c_4 = 0$$

$$(y(0) = \alpha, y(1) = \beta \quad \Rightarrow \quad c_0 = \alpha, c_4 = \beta)$$

Unknowns : c_1, c_2, c_3

$$\text{Equations : } \int_0^1 y_h' \phi_j' dx = \int_0^1 \phi_j dx$$

$$1 \leq j \leq 3.$$

$$\Rightarrow \int_0^1 \left(\sum_{i=1}^3 c_i \phi_i' \right)' \phi_j' dx = \int_0^1 \phi_j dx$$

$$\Rightarrow \sum_{i=1}^3 c_i \int_0^1 \phi_i' \phi_j' dx = \int_0^1 \phi_j dx$$

$$\underbrace{\int_0^1 \phi_i' \phi_j' dx}_{a(\phi_i, \phi_j)} \quad \underbrace{\int_0^1 \phi_j dx}_{b(\phi_j)}$$

$$\Rightarrow \begin{bmatrix} a(\phi_1, \phi_1) & a(\phi_2, \phi_1) & a(\phi_3, \phi_1) \\ a(\phi_1, \phi_2) & a(\phi_2, \phi_2) & a(\phi_3, \phi_2) \\ a(\phi_1, \phi_3) & a(\phi_2, \phi_3) & a(\phi_3, \phi_3) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} b(\phi_1) \\ b(\phi_2) \\ b(\phi_3) \end{bmatrix}$$

$$(A\vec{c} = \vec{b})$$

$$\begin{aligned} \hookrightarrow a(\phi_1, \phi_1) &= \int_0^{0.5} \phi_1' \phi_1' dx \\ &= (0.25)[4^2 + (-4)^2] = 8 \end{aligned}$$

$$a(\phi_2, \phi_1) =$$

$$a(\phi_3, \phi_1) = 0$$

$$\Rightarrow A\vec{c} = \vec{b}, \text{ where}$$

$$A = \begin{bmatrix} 8 & -4 & 0 \\ -4 & 8 & -4 \\ 0 & -4 & 8 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 0.25 \\ 0.25 \\ 0.25 \end{bmatrix}$$

$$\text{because } b(\phi_j) = \int_0^1 \phi_j dx = \frac{1}{2} \times 1 \times 0.5.$$